## PEN Emulator Workshop Lab 1: Brief recap of GPs

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- A likelihood relating the unknown function f(x) to the data y, e.g.

$$y_i = f(x_i) + \epsilon_i$$
 where  $\epsilon_i \sim N(0, \sigma^2)$ 

with  $\epsilon_i \perp \epsilon_j$  for  $i \neq j$ .

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Then inference consists of

- A Bayesian updating scheme to infer  $\pi(f(x)|D,\psi)$ .
- An approach to estimate the hyper-parameters,  $\psi$ .

## Mean functions

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The UQ/emulator world tends to put more effort into choosing a good parametric form for  $m(x) = \beta x$ , as their data is often sparse, and so a strong parametric component can help (or sometimes hinder...) predictions in regions where we lack data.

#### Covariance functions/kernels

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If k is stationary, then we can write k(x, x') = k(x - x'). The differentiability of the sample paths matches the differentiability of k(r) at r = 0, i.e., if k(r) is twice differentiable, then the sample paths will be twice differentiable.

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Covariance functions are often parameterized in terms of hyperparameters, e.g.,

$$k(x, x') = \sigma^2 \exp(-(x - x')^2 / \lambda^2)$$

Here  $\sigma^2$  controls the variance of the sample paths, and  $\lambda$  determines their length-scale.

 Rough rule of thumb: if |x - x'| > 2λ then f(x) and f(x') are close to being uncorrelated.

#### Posterior inference

**The** main reason for using GPs is that if  $f(\cdot) \sim GP(m(\cdot), k(\cdot))$ , then if we observe data  $(x_i, y_i)$ 

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Some exceptions:

- If  $\epsilon$  has a non-Gaussian distribution, then we need to use an alternative updating scheme.
- If *n* is large, then the full Bayesian updating can be prohibitively expensive, as we have to invert a  $n \times n$  matrix (cost  $O(n^3)$ ). There are sparse methods to reduce this cost (included in GPy) that allow us to work with larger datasets.

- If we know the hyper-parameters, working with GPs is a pleasant experience, and the theory is beautiful and simple.
- But if we need to estimate hyper-parameters, then everything gets much trickier.

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- Cross-validation
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Sometimes we need to resort to tricks such as constraining values to lie in some interval (or placing a prior distribution on them), or fixing them at sensible values by hand.

# GPy

GPs are not usually robust models that we can treat as magic black-boxes.

- GPy is probably the most complete GP implementation, written by people deeply involved in the GP world.
- GP fitting can often go wrong.
  - Hyper-parameter optimization is usually the problem.
  - Try constraining the hyper parameters using your judgement.

You must check your model in some way.

- Plot your fitted model
- Test its predictive skill (held out data, or cross-validation)
- The optimized value of the log-likelihood tells you how good a fit you've found the larger the better, but it does not indicate predictive skill.